

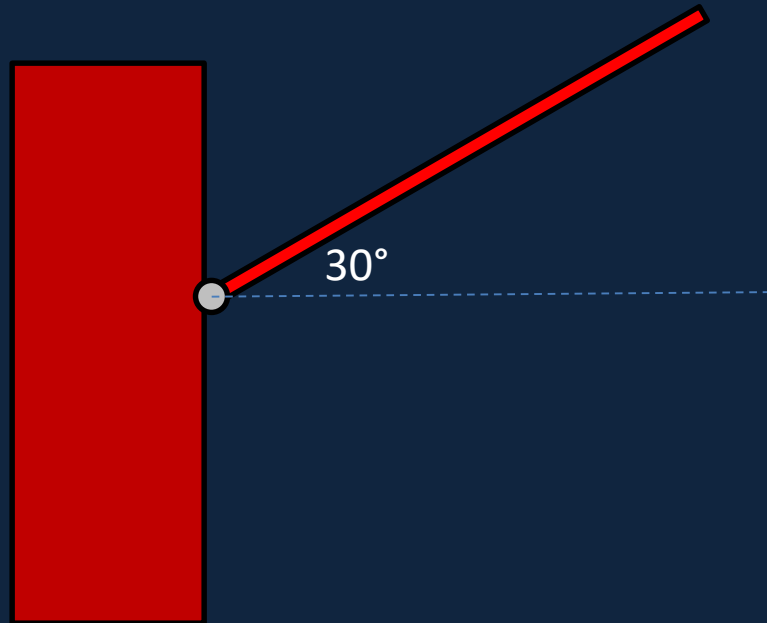
# More Rotational Dynamics

Physics 1425 Lecture 20

# Clicker Question

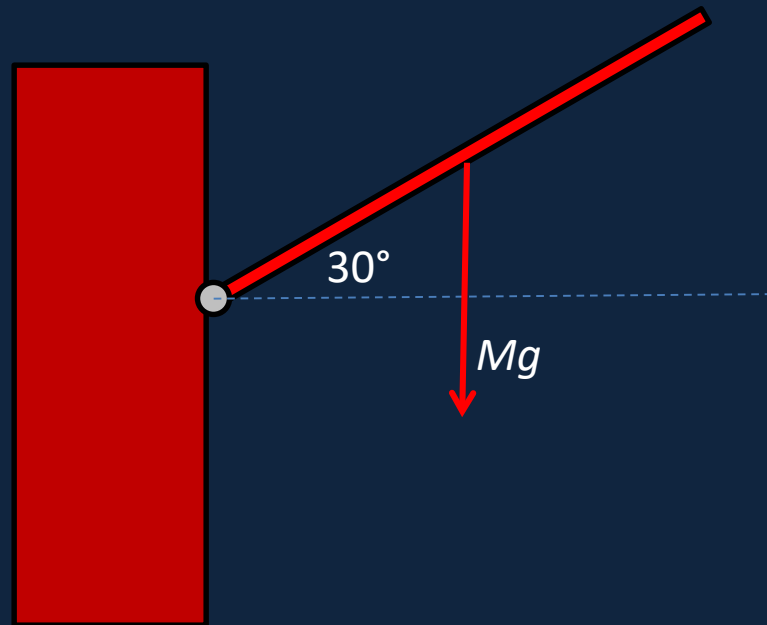
A uniform rod is free to rotate in a vertical plane about a frictionless hinge at one end. It is released from rest at an angle of  $30^\circ$ . ( $I = (1/3)ML^2$ ,  $\tau = Mg(L/2)\cos 30^\circ$ )  
The initial **downward acceleration of the free end** of the rod is:

- A. equal to  $g$
- B. greater than  $g$
- C. less than  $g$



# Clicker Answer

It's *greater* than  $g$ ! The moment of inertia about the hinge is  $(1/3)ML^2$ , the torque is  $(MgL/2)\cos 30^\circ$ , so the acceleration is given by  $\tau = I\alpha$ ,  $\alpha = (3g/2L)\cos 30^\circ$ , the far end accelerates at  $L\alpha = (3g/2)\cos 30^\circ > g$ .



# Rotational Kinetic Energy

- Imagine a rotating body as composed of many small masses  $m_i$  at distances  $r_i$  from the axis of rotation.
- The mass  $m_i$  has speed  $v = \omega r_i$ , so  $KE = \frac{1}{2}m_i r_i^2 \omega^2$ .
- The total  $KE$  of the rotating body (**assuming the axis is at rest**) is

$$K = \sum_i \left( \frac{1}{2} m_i r_i^2 \right) \omega^2 = \frac{1}{2} I \omega^2$$

# Torque Power

- If a net torque  $\tau$  is acting on a rotating body, the net power is the rate of change of rotational energy

$$\frac{d}{dt} \left( \frac{1}{2} I \omega^2 \right) = I \omega \frac{d\omega}{dt} = I \omega \alpha = \omega \tau \quad (\text{recall } \tau = I \alpha)$$

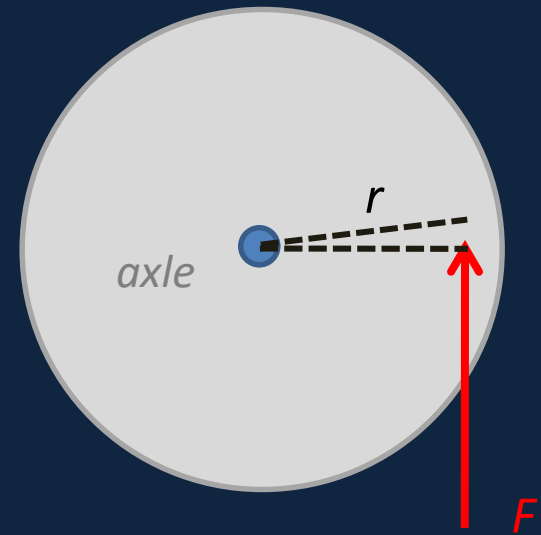
- So the **rate of working** of the torque, **power** =  $\tau \omega$ , its value x the angular velocity.
- Total work done over some time period is

$$\int \tau \omega dt = \int \tau \frac{d\theta}{dt} dt = \int \tau d\theta$$

- This is just like  $\int F dx$  in linear motion.

# Work Done by a Torque

- Suppose the torque is a force  $F$  acting at a distance  $r$  from the center as shown. If the disk turns through an angle  $d\theta$ , the force acts through a distance  $ds = rd\theta$  so does work  $Fds = Frd\theta$ .

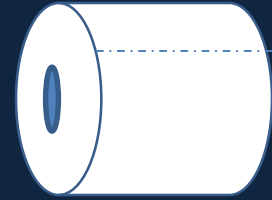


- But  $\tau = rF$ , so the work

$$Fds = Frd\theta = \tau d\theta$$

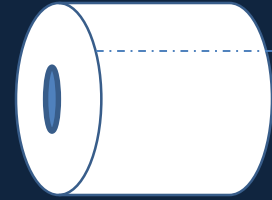
Force x distance = torque x angle

# A Familiar Item...

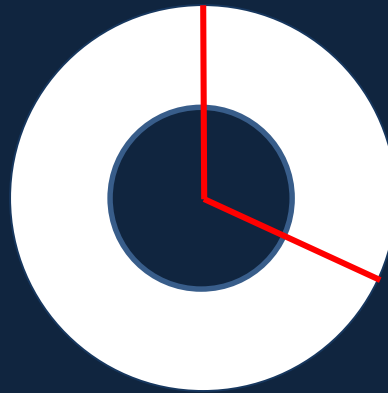


- A roll of toilet paper has diameter 0.1m, which happens also to be the length of one sheet.
- What is the angle *in radians* subtended at the central line of the roll by one sheet in the outside layer?
- A. 1
- B. 2
- C. 0.5
- D.  $\pi$
- E.  $1/\pi$

# A Familiar Item...



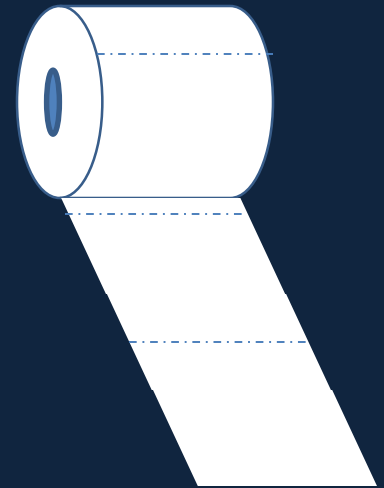
- A roll of toilet paper has diameter 0.1m, which happens also to be the length of one sheet.
- What is the angle *in radians* subtended at the central line of the roll by one sheet in the outside layer?
- It's about 2 radians:





# On a Roll...

- This roll (0.1 m diameter, 0.1 m sheets) rolls across the table, unwinding three sheets per second.
- Give its CM velocity, *and* the angular velocity about the CM in radians/sec.
  - A. 0.3, 6
  - B. 0.3, 3
  - C. 0.6, 6
  - D. 0.3,  $3\pi$



# On a Roll...

- This roll (0.1 m diameter, 0.1 m sheets) rolls across the table, unwinding three sheets per second.
- Give its CM velocity, *and* the angular velocity about the CM in radians/sec.

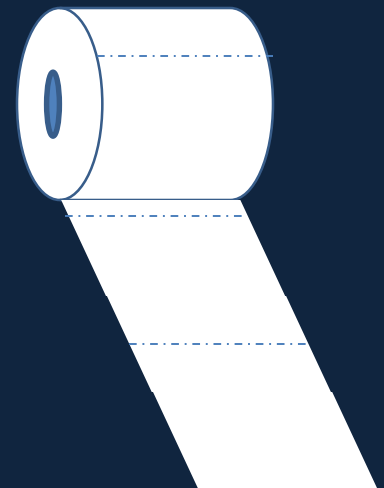
A. 0.3, 6

B. 0.3, 3

C. 0.6, 6

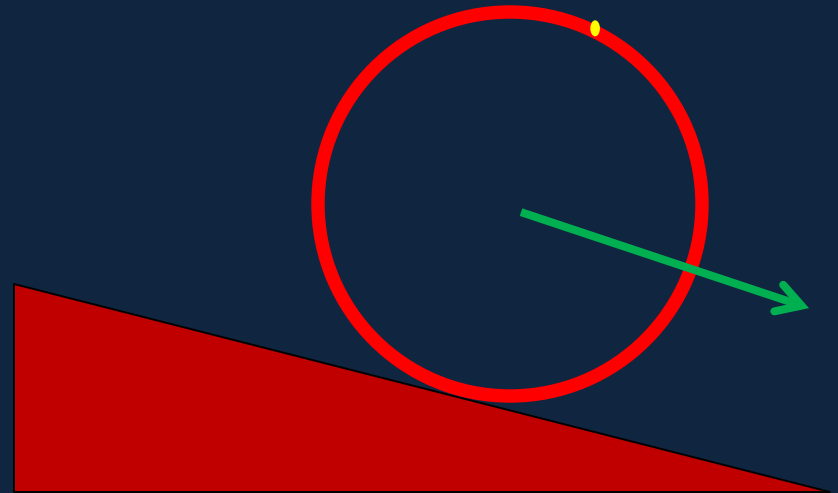
D. 0.3,  $3\pi$

Remember  $\omega = vr$ , and three sheets in one second is 6 radians—almost a complete revolution.



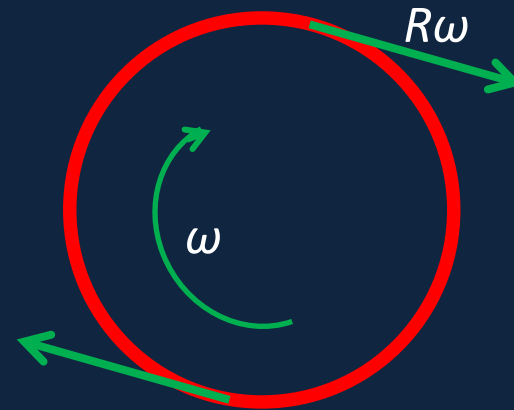
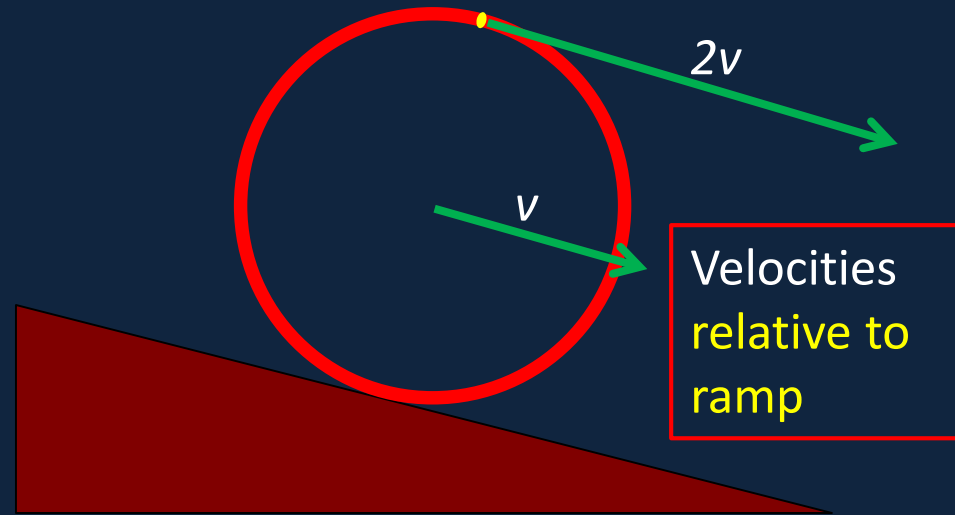
# Clicker Question

- A hoop is rolling down a ramp (without slipping) at  $v$  m/sec.
- How fast is the **point** on the hoop **furthest** from the ramp moving?
- A.  $v$  m/sec
- B.  $2v$  m/sec
- C.  $4v$  m/sec



# Hoop Rolling Down Ramp

- If there's no slipping, the point on the hoop in contact with the ramp is at rest—the hoop is at that instant rotating about that point.
- So if the center is moving at  $v$ , the “top” point is moving at  $2v$ .
- Relative to the center, all points are moving at speed  $R\omega$  tangentially.
- Hence, since the bottom's at rest:  $v = R\omega$
- The “no slip” condition.



# Total Kinetic Energy of Rolling Hoop

- Suppose as usual the hoop is made of many small masses  $m_i$  and the mass  $m_i$  is moving at  $\vec{v}_i$ . Then the **total KE** is  $\sum_i \frac{1}{2} m_i \vec{v}_i^2$ .
- This total kinetic energy depends on **both** the **translational motion** (the center of the hoop is moving) **and** the hoop's **rotation** about the center.
- How do we sort this out?

# Separating Translational and Rotational Kinetic Energies: Details

- Suppose we have **rigid body** we represent as a collection of masses  $m_i$ , with individual velocities  $\vec{v}_i$ .
- Let's suppose the CM is moving at  $\vec{v}_{\text{CM}}$ , so the total **linear** momentum is  $M \vec{v}_{\text{CM}}$ ,  $M$  being the total mass.
- To **separate out the rotational motion**, we'll write the individual velocities  $\vec{v}_i = \vec{v}_{\text{CM}} + \vec{u}_i$ : so  $\vec{u}_i$  is velocity of  $m_i$  relative to the CM.
- Then the total kinetic energy is

$$\sum_i \frac{1}{2} m_i \vec{v}_i^2 = \sum_i \frac{1}{2} m_i (\vec{v}_{\text{CM}} + \vec{u}_i)^2 = \frac{1}{2} M \vec{v}_{\text{CM}}^2 + \vec{v}_{\text{CM}} \cdot \sum_i m_i \vec{u}_i + \sum_i \frac{1}{2} m_i \vec{u}_i^2$$

$$KE = \frac{1}{2} M \vec{v}_{\text{CM}}^2 + \frac{1}{2} I_{\text{CM}} \omega^2$$

- Because relative to the CM  $\sum_i m_i \vec{u}_i = \frac{d}{dt} \sum_i m_i \vec{r}_i = 0$ ,  $\vec{u}_i^2 = r_i^2 \omega^2$ .

# Total Energy: the Bottom Line

- In case the last slide was too much, what you *really* need is that the **total kinetic energy** of a moving, rotating object **is a sum of two terms**:
- **Translational KE**, the same as if all the mass is moving with the velocity of the center of mass, **and**
- **Rotational KE**, about the center of mass:

$$KE = \frac{1}{2} M \vec{v}_{CM}^2 + \frac{1}{2} I_{CM} \omega^2$$

# How Fast Does a Hoop Roll Down a Ramp?

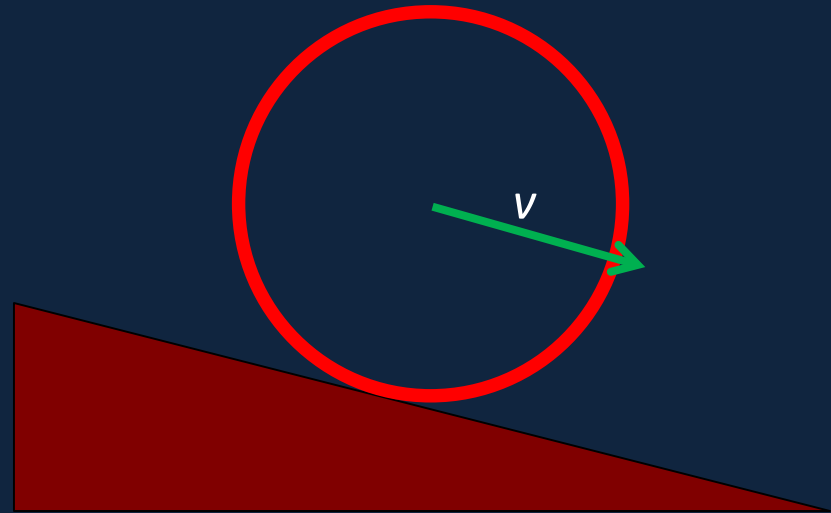
- Assuming no slipping, so

$$v = R\omega$$

- The total kinetic energy at an instant:

$$\begin{aligned} KE &= \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 \\ &= \frac{1}{2}mv^2 + \frac{1}{2}(mR^2)\omega^2 \\ &= mv^2. \end{aligned}$$

- If it's rolled down through height  $h$  from a standing start,  $mv^2 = mgh$ , so  $v = \sqrt{gh}$
- For a frictionless sliding mass,  $\frac{1}{2}mv^2 = mgh$ , so  $v = \sqrt{2gh}$ : faster!



The hoop takes **longer** to get down than a low-friction sliding block, because the **same** loss in potential energy has to supply **BOTH** translational *KE* and rotational *KE* for the hoop.



## Ramp Race

A hoop, a solid cylinder and a solid sphere roll down the same ramp from a standing start. Who clocks the fastest time?

- A. The hoop
- B. The solid cylinder
- C. The solid sphere
- D. It depends on the sizes and/or masses.

## Ramp Race

A hoop, a solid cylinder and a solid sphere roll down the same ramp from a standing start. Who clocks the fastest time?

The sphere wins: its mass is on average closer to the axis of rotation, so it has less rotational  $KE$  compared with translational  $KE$ .

- A. The hoop
- B. The solid cylinder
- C. The solid sphere
- D. It depends on the sizes and/or masses.

**Note:** for the sphere  $I = (2/5)mR^2$  solid cylinder  $\frac{1}{2}mR^2$ , hoop  $mR^2$ .

# A New Look for $\tau = I\alpha$

- We've seen how  $\tau = I\alpha$  works for a body rotating about a **fixed axis**.
- $\tau = I\alpha$  is not true in general if the axis of rotation is *itself* accelerating
- **BUT it IS true if the axis is through the CM, and isn't changing direction!**
- This is quite tricky to prove—it's in the book
- And  $\tau_{\text{CM}} = I_{\text{CM}}\alpha_{\text{CM}}$  is often useful, as we'll see.